

NUMERICAL STUDY OF A DIFFUSION EQUATION WITH VENTCEL BOUNDARY CONDITION USING CURVED MESHES

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Abstract. In this work is provided a numerical study of a diffusion problem involving a second order term on the domain boundary (the Laplace-Beltrami operator) referred to as the *Ventcel problem*. A variational formulation of the Ventcel problem is studied, leading to a finite element discretization. The focus is on the resort to high order curved meshes for the discretization of the physical domain. The computational errors are investigated both in terms of geometrical error and of finite element approximation error, respectively associated to the mesh degree $r \geq 1$ and to the finite element degree $k \geq 1$. The numerical experiments we led allow us to formulate a conjecture on the *a priori* error estimates depending on the two parameters r and k . In addition, these error estimates rely on the definition of a functional *lift* with adapted properties on the boundary to move numerical solutions defined on the computational domain to the physical one.

Keywords: Laplace-Beltrami operator, Ventcel boundary condition, finite element method, high order meshes, geometric error, *a priori* error estimates.

AMS classification: 74S05, 65N15, 65N30, 65G99.

Introduction

Motivation. On the one hand, in various situations, we have to numerically solve a problem (a partial differential equation) on a non-polygonal geometry. This requires the use of high order meshes in order to well approximate it. On the other hand, in several industrial applications, objects or materials surrounded by a thin layer with potentially other properties (typically a surface treatment or corrosion) have to be considered. The presence of this layer causes some difficulties while discretizing the domain and numerically solving the problem. To overcome this problem, the domain is approximated asymptotically by an other one without a thin layer but equipped with artificial boundary conditions, like *Ventcel boundary condition*. The physical properties of the thin layer are then contained in the boundary condition.

This paper focuses on the resolution of a problem involving higher order boundary condition and numerically evaluates the *a priori* error produced by a finite element approximation on higher order meshes, distinguishing the *geometrical error* from the *approximation error*.

The Ventcel problem and its approximation. Let Ω be a domain in \mathbb{R}^d , $d = 2, 3$, with a smooth boundary Γ . The Laplace-Beltrami operator on Γ is denoted by Δ_Γ . Relatively to the source terms f and g and to the constants $\kappa \geq 0$, $\alpha, \beta > 0$, the Ventcel problem reads,

$$\begin{cases} -\Delta u + \kappa u = f & \text{in } \Omega, \\ -\beta \Delta_\Gamma u + \partial_{\mathbf{n}} u + \alpha u = g & \text{on } \Gamma, \end{cases} \quad (1)$$

with \mathbf{n} the external unit normal to Γ and $\partial_{\mathbf{n}}u$ the normal derivative of u along Γ . The theoretical properties of the solution of problem (1) have been studied in [10].

Due to the presence of the second order term in the boundary condition, the domain Ω is required to be smooth and thus non-polygonal: from the numerical point of view, the computational domain Ω_h (the mesh domain) will not fit the physical one: $\Omega_h \neq \Omega$. In a context of finite element methods of high order $k \geq 2$, it then is necessary to resort to high order meshes of geometrical degree $r \geq 2$ to preserve the numerical solution's accuracy. Some methods have been widely studied, see, *e.g.*, [7, 6, 5, 14, 12].

The approximation of the Laplace equation on a surface has been studied in this framework by Demlow *et al.* in [3, 4]. In these works, a distinction is made between the geometrical error induced by the setting of the computational domain $\Omega_h \neq \Omega$ and the approximation error related to the finite element method. The purpose of this approach is to highlight the influence of the geometrical degree r of the mesh and the finite element approximation degree k on the total computational error. Thereby, one can assess which is the optimal degree of the finite element method k to chose depending on the choice of the geometrical degree r . To the authors' knowledge, no such estimations have been made for the Ventcel problem (1). Though, in [7], similar estimations are done in the isoparametric case.

In the present context where $\Omega_h \neq \Omega$, a crucial issue arises: how does one compare the numerical solutions u_h to the exact one, in order to derive *a priori* error estimates? To circumvent this, a lift of u_h onto Ω is defined: in [5], Dubois introduced such a lift based on the orthogonal projection onto the boundary Γ , which further was improved in terms of regularity by Elliott *et al.* [7]. This lift however does not fit the orthogonal projection on the computational domain boundary. An alternative definition is introduced in this paper which will be used to perform a numerical study of the computational error of problem (1). Better numerical results are obtained when using the new lift operator, as discussed in Section 3.

Paper organization. In section 1, after introducing some general mathematical tools, is stated and proven the well-posedness of the Ventcel problem (1). The following section 2 is devoted to the definition of the curved meshes of Ω . In section 3 are presented the discretization of the Ventcel problem (1), the lift operator which is the keystone of the *a priori* error estimations and numerical experiments studying the method convergence rate depending on the mesh geometrical degree r and on the finite element approximation degree k . The paper ends with a conclusion section presenting our conjecture on *a priori* error estimates.

§1. Study of the Ventcel problem

Some mathematical tools. Let us denote Ω a bounded connected open subset of \mathbb{R}^d with a smooth boundary $\Gamma := \partial\Omega$ at least of C^2 regularity. The unit normal to Γ pointing outwards is denoted by \mathbf{n} . The classical spaces $L^2(\Omega)$, $L^2(\Gamma)$, $H^1(\Omega)$ and $H^1(\Gamma)$ are considered and we introduce the following Hilbert space and its associated norm (see [10, Lemma 2.5])

$$H^1(\Omega, \Gamma) := \{u \in H^1(\Omega), u|_{\Gamma} \in H^1(\Gamma)\}, \quad \|u\|_{H^1(\Omega, \Gamma)}^2 := \|u\|_{H^1(\Omega)}^2 + \|u|_{\Gamma}\|_{H^1(\Gamma)}^2.$$

We consider the classical surface operators (see, *e.g.*, [9, p. 192-196]):

- the *tangential gradient* of $u \in H^1(\Gamma)$ is given by $\nabla_\Gamma u := \nabla \tilde{u} - (\nabla \tilde{u} \cdot \mathbf{n})\mathbf{n}$, where $\tilde{u} \in H^1(\mathbb{R}^d)$ is any extension of u ;
- the *tangential divergence* of $W \in [H^1(\Gamma)]^d$ is $\operatorname{div}_\Gamma W := \operatorname{div} \tilde{W} - (D\tilde{W} \mathbf{n}) \cdot \mathbf{n}$, where $\tilde{W} \in [H^1(\mathbb{R}^d)]^d$ is any extension of W and $D\tilde{W}$ is the differential of \tilde{W} ;
- the *Laplace-Beltrami operator* of $u \in H^2(\Gamma)$ is given by $\Delta_\Gamma u := \operatorname{div}_\Gamma(\nabla_\Gamma u)$.

Finally, the following fundamental result is recalled, see, e.g., [2] and [8, §14.6].

Proposition 1. *Let Ω and $\Gamma = \partial\Omega$ be as stated previously. Let $d : \mathbb{R}^d \rightarrow \mathbb{R}$ be the signed distance function with respect to Γ defined by,*

$$d(x) := \begin{cases} -\operatorname{dist}(x, \Gamma) & \text{if } x \in \Omega, \\ 0 & \text{if } x \in \Gamma, \\ \operatorname{dist}(x, \Gamma) & \text{otherwise,} \end{cases} \quad \text{with } \operatorname{dist}(x, \Gamma) := \inf\{|x - y|, y \in \Gamma\}.$$

Then there exists a tubular neighborhood \mathcal{U}_Γ of Γ where d is a C^2 function. Its gradient ∇d is an extension of the external unit normal \mathbf{n} to Γ . Additionally, in this neighborhood \mathcal{U}_Γ , the orthogonal projection b onto Γ is uniquely defined and given by

$$b : x \in \mathcal{U}_\Gamma \mapsto b(x) := x - d(x)\nabla d(x) \in \Gamma.$$

Well-posedness of problem (1). The weak form of (1) is to find $u \in H^1(\Omega, \Gamma)$ such that,

$$\forall v \in H^1(\Omega, \Gamma), \quad a(u, v) = l(v) := \int_\Omega f v dx + \int_\Gamma g v d\sigma, \quad (2)$$

where $a(\cdot, \cdot)$ is defined on $H^1(\Omega, \Gamma)^2$ by:

$$a(u, v) := \int_\Omega \nabla u \cdot \nabla v dx + \kappa \int_\Omega u v dx + \beta \int_\Gamma \nabla_\Gamma u \cdot \nabla_\Gamma v d\sigma + \alpha \int_\Gamma u v d\sigma. \quad (3)$$

Notice that the weak form (2) is equivalent to the system introduced in (1) as it was proven in [10].

Theorem 2. *Let Ω and $\Gamma = \partial\Omega$ be as stated previously. Let $\alpha, \beta > 0$, $\kappa \geq 0$, and $f \in L^2(\Omega)$, $g \in L^2(\Gamma)$. Then there exists a unique solution $u \in H^1(\Omega, \Gamma)$ to problem (2).*

The proof of this theorem is classical and is briefly given in [10, th. 3.2]. We detail it here for the sake of completeness. Let us notice that, additionally, it is proven in [10, th. 3.3] that there exists a (source term independent) constant $c > 0$ such that

$$\|u\|_{H^2(\Omega, \Gamma)} \leq c(\|f\|_{L^2(\Omega)} + \|g\|_{L^2(\Gamma)}).$$

Proof. The proof relies on the Lax-Milgram theorem. The linear form $l(\cdot)$ in (2) and the bilinear form $a(\cdot, \cdot)$ in (3) being continuous respectively on $H^1(\Omega, \Gamma)$ and on $H^1(\Omega, \Gamma)^2$, it remains to show that a is coercive. We must distinguish between two cases.

1) **If $\kappa \neq 0$.** The result is obvious: for all $u \in H^1(\Omega, \Gamma)$, $a(u, u) \geq \min\{1, \kappa, \alpha, \beta\} \|u\|_{H^1(\Omega, \Gamma)}^2$.

2) **If $\kappa = 0$.** We proceed by contradiction assuming that there exists a sequence $(u_n)_{n \in \mathbb{N}^*}$ in $H^1(\Omega, \Gamma)$ such that for all $n \geq 1$,

$$\|\nabla u_n\|_{L^2(\Omega)}^2 + \beta \|\nabla_\Gamma u_n\|_{L^2(\Gamma)}^2 + \alpha \|u_n\|_{L^2(\Gamma)}^2 < \frac{1}{n} (\|u_n\|_{H^1(\Omega)}^2 + \|u_n\|_{H^1(\Gamma)}^2).$$

It follows that $u_n \neq 0$ for all $n \geq 1$. Thus u_n can be renormalized such that $\|u_n\|_{H^1(\Omega, \Gamma)} = 1$ and it satisfies $\|\nabla u_n\|_{L^2(\Omega)}^2 + \beta \|\nabla_{\Gamma} u_n\|_{L^2(\Gamma)}^2 + \alpha \|u_n\|_{L^2(\Gamma)}^2 < \frac{1}{n}$. Therefore

$$\nabla u_n \rightarrow 0 \quad \text{in } L^2(\Omega), \quad \nabla_{\Gamma} u_n \rightarrow 0 \quad \text{in } L^2(\Gamma) \quad \text{and} \quad u_n \rightarrow 0 \quad \text{in } L^2(\Gamma). \quad (4)$$

Since $(u_n)_n$ is bounded in $H^1(\Omega, \Gamma)$, there exists $u \in H^1(\Omega, \Gamma)$ such that $u_n \rightharpoonup u$ in $H^1(\Omega, \Gamma)$, and since $H^1(\Omega, \Gamma) \hookrightarrow L^2(\Omega, \Gamma)$ is a compact injection, we obtain

$$u_n \rightarrow u \quad \text{in } L^2(\Omega, \Gamma). \quad (5)$$

Passing to the limit in $\|u_n\|_{H^1(\Omega, \Gamma)}^2 = \|\nabla u_n\|_{L^2(\Omega)}^2 + \|\nabla_{\Gamma} u_n\|_{L^2(\Gamma)}^2 + \|u_n\|_{L^2(\Gamma)}^2 + \|u_n\|_{L^2(\Omega)}^2 = 1$, and using the convergences given in (4) and (5), we obtain $\|u\|_{L^2(\Omega, \Gamma)}^2 = 1$. However, since $\nabla u_n \rightharpoonup \nabla u$ in $L^2(\Omega)$, we use (4) and the uniqueness of the limit to obtain $\nabla u = 0$ and, since Ω is a connected set, it follows that $u = C \in \mathbb{R}$. Finally, $u_n \rightarrow u$ in $L^2(\Gamma)$ and also $u_n \rightarrow 0$ in $L^2(\Gamma)$, these two points yield $u = 0 = C$ which contradicts $\|u\|_{L^2(\Omega, \Gamma)} = 1$ and concludes the proof of the coercivity. \square

§2. Curved mesh definition

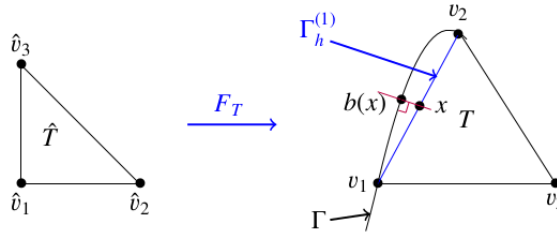
In this section are defined curved meshes of geometrical degree $r \geq 1$ of the domain Ω . From now on, the domain $\Omega \subset \mathbb{R}^d$, $d=2$ or 3 , is assumed to be at least C^{r+2} regular, and \hat{T} denotes the reference simplex of dimension d . The definition steps are the following (see [7, 14, 5] for more details).

1. Construct an affine mesh $\mathcal{T}_h^{(1)}$ of Ω composed of simplexes T .
2. For each $T \in \mathcal{T}_h^{(1)}$, a mapping $F_T^{(e)} : \hat{T} \rightarrow T^{(e)} := F_T^{(e)}(\hat{T})$ is designed, so that the *exact element* $T^{(e)}$ form a curved mesh $\mathcal{T}_h^{(e)}$ whose domain exactly fits Ω .
3. For each $T \in \mathcal{T}_h^{(1)}$, the mapping $F_T^{(e)}$ is interpolated by a polynomial $F_T^{(r)}$ of degree r . The associated elements $T^{(r)} := F_T^{(r)}(\hat{T})$ form a curved mesh $\mathcal{T}_h^{(r)}$ of degree r of Ω .

Affine mesh. Let $\mathcal{T}_h^{(1)}$ be a mesh of Ω made of simplexes of dimension d (triangles or tetrahedra), it is chosen as quasi-uniform and henceforth shape-regular (see [1, def. 4.4.13]). The mesh domain is denoted by $\Omega_h^{(1)} := \cup_{T \in \mathcal{T}_h^{(1)}} T$ and its boundary by $\Gamma_h^{(1)} := \partial\Omega_h^{(1)}$, which is composed of $(d-1)$ -dimensional simplexes that form a mesh of $\Gamma = \partial\Omega$. The vertices of $\Gamma_h^{(1)}$ are assumed to lie on Γ . We define the mesh size $h := \max\{\text{diam}(T); T \in \mathcal{T}_h^{(1)}\}$. To each $T \in \mathcal{T}_h^{(1)}$ is associated an affine function $F_T : \hat{T} \rightarrow T = F_T(\hat{T})$.

Remark 1. For a sufficiently small h , the mesh boundary satisfies $\Gamma_h^{(1)} \subset \mathcal{U}_{\Gamma}$, where \mathcal{U}_{Γ} is the tubular neighborhood given in proposition 1. This guaranties that the orthogonal projection $b : \Gamma_h^{(1)} \rightarrow \Gamma$ is one to one which is required for the construction of the exact mesh.

Example 1. In the two dimensional case is displayed the case of a triangle $T \in \mathcal{T}_h^{(1)}$, with $T \cap \Gamma = \{v_1, v_2\}$, together with the mapping F_T that maps \hat{T} into T .



Exact mesh $\mathcal{T}_h^{(e)}$. After the early works of Scot [14] and Lenoir [11] defining transformations towards curved elements, Dubois [5] first introduced a definition based on the orthogonal projection b onto Γ , further developed by Elliott *et al.* [7, §4] in terms of regularity, which definition is recalled here.

Let us first point out that, because of the quasi uniform assumption made on the mesh $\mathcal{T}_h^{(1)}$, and for h sufficiently small, a mesh element T cannot have $d + 1$ vertices on the boundary Γ . We define internal elements as those having at most one vertex on the boundary Γ , whereas other elements have:

- 2 vertices on the boundary in the two dimensional case;
- 2 or 3 vertices on Γ in the 3D case, forming either an edge or a face respectively.

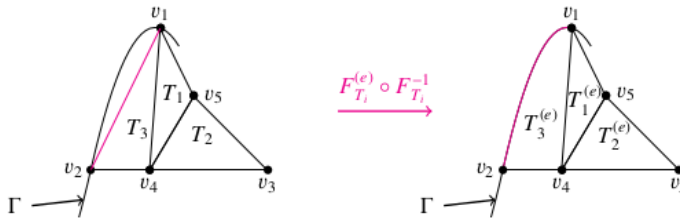
The case of internal elements is skipped by setting $F_T^{(e)} = F_T$.

Let then $T \in \mathcal{T}_h^{(1)}$ a non-internal element, denote $v_i = F_T(\hat{v}_i)$ its vertices, \hat{v}_i being the vertices of \hat{T} , and define $\varepsilon_i = 1$ if $v_i \in \Gamma$ or $\varepsilon_i = 0$ otherwise. To $\hat{x} \in \hat{T}$ is associated its barycentric coordinates λ_i associated to the vertices \hat{v}_i of \hat{T} . We introduce $\lambda^* := \sum_{i=1}^{d+1} \varepsilon_i \lambda_i$ and $\hat{y} := \frac{1}{\lambda^*} \sum_{i=1}^{d+1} \varepsilon_i \lambda_i \hat{v}_i \in \hat{T}$. The mapping $F_T^{(e)} : \hat{T} \rightarrow T^{(e)}$ is given by,

$$F_T^{(e)}(\hat{x}) := x + (\lambda^*)^{r+2}(b(y) - y), \quad \text{with } x = F_T(\hat{x}) \quad \text{and} \quad y = F_T(\hat{y}). \quad (6)$$

Remark 2. For $x \in T \cap \Gamma_h$, we have that $\lambda^* = 1$ and so $y = x$ inducing that $F_T^{(e)}(\hat{x}) = b(x)$: $F_T^{(e)} \circ F_T^{-1} = b$ on $T \cap \Gamma_h$ which is then mapped on Γ following the orthogonal projection b . The mapping $F_T^{(e)}$ has been shown in [7] to be C^{r+1} regular on \hat{T} .

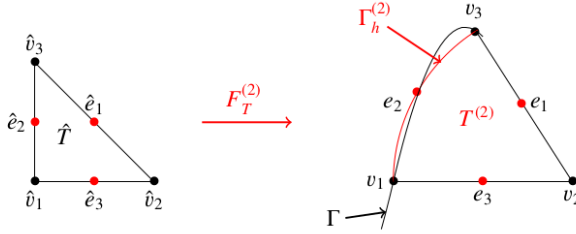
Example 2. Consider three triangles T_1, T_2 and T_3 in \mathbb{R}^2 as displayed below. For $i = 1, 2, 3$, we have the following transformation $F_{T_i}^{(e)} \circ F_{T_i}^{-1}$ that maps $T_i \in \mathcal{T}_h^{(1)}$ into $T_i^{(e)}$ as follows,



T_1 and T_2 are internal and so are unchanged whereas T_3 (having 2 vertices on Γ) is not internal and mapped into a curved triangle with an edge exactly fitting Γ .

Curved mesh $\mathcal{T}_h^{(r)}$ with degree r . Let $T \in \mathcal{T}_h^{(1)}$ and $r \geq 1$, the exact mapping $F_T^{(e)}$ in (6) is interpolated as a polynomial of degree r in the classical \mathbb{P}^r -Lagrange basis on \hat{T} . The interpolant is denoted by $F_T^{(r)}$ and we define $T^{(r)} := F_T^{(r)}(\hat{T})$. The curved mesh of degree r is $\mathcal{T}_h^{(r)} := \{T^{(r)}; T \in \mathcal{T}_h^{(1)}\}$ with domain $\Omega_h^{(r)} := \cup_{T^{(r)} \in \mathcal{T}_h^{(r)}} T^{(r)}$ and with boundary $\Gamma_h^{(r)} := \partial\Omega_h^{(r)}$. Note that $F_T^{(r)}(v) = F_T^{(e)}(v)$ for v a \mathbb{P}^r -Lagrange node in \hat{T} .

Example 3. In the quadratic case $r = 2$ is displayed a border quadratic element $T^{(2)}$. The mappings $F_T^{(2)}$ and $F_T^{(e)}$ coincide at the \mathbb{P}^2 -Lagrange nodes which are the three vertexes \hat{v}_i and the three edge mid-points \hat{e}_i of \hat{T} .



§3. Numerical experiments

Functional lift. Here, we define *lifts* to transform a function on a domain $\Omega_h^{(r)}$ or $\Gamma_h^{(r)}$ (defined in the previous section) into a function defined on Ω or Γ respectively. Lifts are necessary for two reasons: to compare the numerical solutions to the exact one and thus perform *a priori* error estimates, but also to define the right hand side source terms in the numerical formulation of problem (1).

A surface lift is obviously provided by the orthogonal projection $b : \Gamma_h^{(r)} \rightarrow \Gamma$, to $v_h \in L^2(\Gamma_h^{(r)})$ is associated $v_h^L \in L^2(\Gamma)$ given by $v_h^L \circ b = v_h$.

To define a volume lift, a transformation $G_h^{(r)} : \Omega_h^{(r)} \rightarrow \Omega$ is defined and then to $u_h \in L^2(\Omega_h^{(r)})$ is associated $u_h^L \in L^2(\Omega)$ given by $u_h^L \circ G_h^{(r)} = u_h$. The definition of $G_h^{(r)}$ is less obvious and we describe it here.

In [7], it is given piecewise on all $T^{(r)} \in \mathcal{T}_h^{(r)}$ by $G_{h|_{T^{(r)}}} := F_T^{(e)} \circ (F_T^{(r)})^{-1}$, where T is the affine element relative to $T^{(r)}$. However, this transformation does not fit the orthogonal projection b on the mesh boundary. Precisely, following remark 2, for $x \in \Gamma_h^{(r)} \cap T^{(r)}$, $G_h(x) := b \circ F_T \circ (F_T^{(r)})^{-1}(x)$. As a result the surface and bulk lifts do not coincide on $\Gamma_h^{(r)} : (\text{Tr } u_h^L)^L \neq \text{Tr}(u_h^L)$, where Tr refers to the trace operator.

To avoid this, we propose the following alternative definition of $G_h^{(r)}$ that is given piecewise for all $T^{(r)} \in \mathcal{T}_h^{(r)}$ by (with the notations of equation (6)),

$$G_h^{(r)}|_{T^{(r)}} := F_T^{(e)} \circ (F_T^{(r)})^{-1}, \quad F_T^{(e)}(\hat{x}) := x + (\lambda^*)^{r+2}(b(y) - y), \quad x = F_T^{(r)}(\hat{x}) \quad \text{and} \quad y = F_T^{(r)}(\hat{y}). \quad (7)$$

Geometrically, $T^{(r)}$ is directly transformed into $T^{(e)}$ by $F_T^{(e)} \circ (F_T^{(r)})^{-1}$, without being first transformed into T as previously done. Now, for $x \in F_T^{(r)} \cap \Gamma_h^{(r)}$, $\hat{x} = (F_T^{(r)})^{-1}(x)$ satisfies

$\lambda^* = 1$ and so $\hat{y} = \hat{x}$ and $y = x$. So $F_{T(r)}^{(e)}(\hat{x}) = b(x)$, the volume and surface lifts both coincide with b on $\Gamma_h^{(r)}$ and the expected relation,

$$\forall u_h \in H^1(\Omega_h^{(r)}), \quad (\text{Tr } u_h)^L = \text{Tr}(u_h^\ell),$$

now holds. Consequently, the surface lift v_h^L now simply will be denoted by v_h^ℓ .

Finite element formulation and implementation. On a mesh $\mathcal{T}_h^{(r)}$ is considered the finite element space,

$$V_h := \left\{ u \in C^0(\Omega_h^{(r)}), \forall T \in \mathcal{T}_h^{(r)}, u|_T \circ F_T^{(r)} \in \mathbb{P}^k(\hat{T}) \right\}, \quad (8)$$

with $\mathbb{P}^k(\hat{T})$ the polynomials of degree k on \hat{T} and with $k \geq 1$ the finite element degree. Following [7], the problem (1) is discretized as: find $u_h \in V_h$ such that,

$$\forall v_h \in V_h, \quad a_h(u_h, v_h) = l_h(v_h) := \int_{\Omega_h^{(r)}} f^{-\ell} J_{G_h^{(r)}} dx + \int_{\Gamma_h^{(r)}} g^{-\ell} J_b d\sigma, \quad (9)$$

with $G_h^{(r)}$ defined in (7), with $f^{-\ell} := f \circ G_h^{(r)}$ and $g^{-\ell} := g \circ b$ the inverse lifts of the source terms in (1), with $J_{G_h^{(r)}}$ and J_b the Jacobians of $G_h^{(r)}$ and $b_{\Gamma_h^{(r)}}$ respectively and where a_h is the bilinear form in (3) rewritten on $\Omega_h^{(r)}$ and $\Gamma_h^{(r)}$.

Finite element space definition, matrix assembling and computation on curved surfaces are led using the code Cumin [13]. All integral computations rely on quadrature rules on the reference elements which are always chosen of sufficient order without further details.

Laplace equation on a surface. In order to validate the code, we first draw our attention towards the Laplace equation $-\Delta_\Gamma u + u = g$ on a smooth surface $\Gamma \subset \mathbb{R}^3$. We refer to Demlow [3, 4] for the analysis of its finite element formulation. Given a mesh $\mathcal{T}_h^{(r)}$ of Γ , following (8), the \mathbb{P}^k -Lagrange finite element space is $W_h := \left\{ u \in C^0(\Gamma_h^{(r)}), \forall T \in \mathcal{T}_h^{(r)}, u|_T \circ F_T^{(r)} \in \mathbb{P}^k(\hat{T}) \right\}$ and the discrete problem is: find $u_h \in W_h$ such that,

$$\forall v_h \in W_h, \quad \int_{\Gamma_h^{(r)}} \nabla_T u_h \cdot \nabla_T v_h d\sigma + \int_{\Gamma_h^{(r)}} u_h v_h d\sigma = \int_{\Gamma_h^{(r)}} v_h g^{-\ell} J_b d\sigma,$$

with $g^{-\ell}$ and J_b previously defined in (9). The *a priori* error estimate for this problem developed by Demlow reads,

$$\|u - u_h^\ell\|_{L^2(\Gamma)} = O(h^{k+1} + h^{r+1}), \quad \|\nabla_\Gamma(u - u_h^\ell)\|_{L^2(\Gamma)} = O(h^k + h^{r+1}), \quad (10)$$

for a smooth enough source term g .

We set Γ to the unit sphere and the source term to $g(x, y, z) = e^y(y + 2)y$. Three series of successively refined meshes, respectively affine, quadratic and cubic, of Γ have been generated by the software Gmsh¹. The numerical errors have been computed for each mesh and for \mathbb{P}^k , with $k = 1, \dots, 4$.

¹Gmsh: a three-dimensional finite element mesh generator, <https://gmsh.info/>

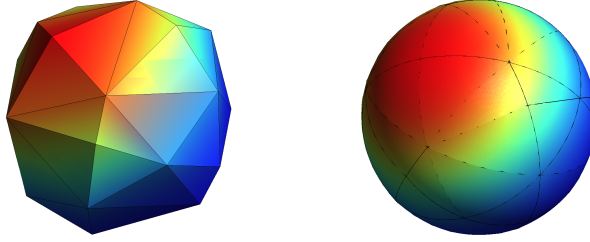


Figure 1: Numerical solution of the Laplace equation on a sphere with affine and quadratic meshes.

	$\ u - u_h^\ell\ _{L^2(\Gamma)}$				$\ u - u_h^\ell\ _{H^1(\Gamma)}$			
	\mathbb{P}^1	\mathbb{P}^2	\mathbb{P}^3	\mathbb{P}^4	\mathbb{P}^1	\mathbb{P}^2	\mathbb{P}^3	\mathbb{P}^4
Affine mesh (r=1)	1.96	1.96	1.96	1.96	0.99	1.96	1.96	1.96
Quadratic mesh (r=2)	1.98	2.95	3.92	3.92	0.98	1.97	3.00	3.91
Cubic mesh (r=3)	1.98	2.94	3.95	3.92	0.98	1.96	2.96	3.95

Table 1: Convergence order for the Laplace equation on a sphere.

The numerical solution on two coarse meshes is depicted on figure 1, and the measured convergence orders are reported in table 1. The affine and cubic meshes behave exactly as expected following (10). In turn, quadratic meshes produce unexpected convergence rates indicated in red in table 1 and a super convergence is observed. Quadratic meshes display a geometrical error h^4 instead of the expected h^3 and thus behave as if $r = 3$. This behavior has been further investigated and is not problem dependent. It is also observed for the Poisson problem on a disk with Neumann or Robin boundary conditions. It is neither caused by the considered geometry: studying a simpler problem of integral computation on a non-symmetric and non-convex domain gave the same surprising super convergence. So far we have no further explanation for this particular error.

Numerical study of the Ventcel problem. The Ventcel problem (1) is considered on the unit disk Ω with $\alpha = \beta = 1$ and $\kappa = 0$, with the source terms $f(x, y) = -ye^x$ and $g(x, y) = ye^x(3 + 4x - y^2)$ corresponding to the exact solution $u = -f$. The discrete problem (9) is implemented and solved using the code Cumin [13]. Again, three series of successively refined meshes, respectively affine, quadratic and cubic, of Ω have been generated with Gmsh. For each mesh and for \mathbb{P}^k finite elements, with $k = 1, \dots, 4$, four numerical errors are computed (two in the bulk domain and two on the boundary),

$$\|u - u_h^\ell\|_{L^2(\Omega)}, \quad \|\nabla(u - u_h^\ell)\|_{L^2(\Omega)}, \quad \|u - u_h^\ell\|_{L^2(\Gamma)} \quad \text{and} \quad \|\nabla_\Gamma(u - u_h^\ell)\|_{L^2(\Gamma)},$$

and the estimated convergence rates are reported in the two tables 2 and 3.

The surface errors in table 2 behave exactly the same way as the estimation (10) for the Laplace equation on a surface: the same super-convergence for the quadratic meshes again occurs, as if $r = 3$ in that case. Thus, the numerical solution seems to be correctly computed.

	$\ u - u_h^\ell\ _{L^2(\Gamma)}$				$\ \nabla_\Gamma(u - u_h^\ell)\ _{L^2(\Gamma)}$			
	\mathbb{P}^1	\mathbb{P}^2	\mathbb{P}^3	\mathbb{P}^4	\mathbb{P}^1	\mathbb{P}^2	\mathbb{P}^3	\mathbb{P}^4
Affine mesh ($r=1$)	2.00	2.03	2.01	2.01	1.00	2.00	1.99	1.98
Quadratic mesh ($r=2$)	2.00	3.00	4.00	4.02	1.00	2.00	3.00	4.02
Cubic mesh ($r=3$)	2.00	3.00	4.00	4.24	1.00	2.00	3.00	3.98

 Table 2: Convergence order of $\|u - u_h^\ell\|_{L^2(\Gamma)}$ and of $\|\nabla_\Gamma(u - u_h^\ell)\|_{L^2(\Gamma)}$

	$\ u - u_h^\ell\ _{L^2(\Omega)}$				$\ \nabla(u - u_h^\ell)\ _{L^2(\Omega)}$			
	\mathbb{P}^1	\mathbb{P}^2	\mathbb{P}^3	\mathbb{P}^4	\mathbb{P}^1	\mathbb{P}^2	\mathbb{P}^3	\mathbb{P}^4
Affine mesh ($r=1$)	1.98	1.99	1.97	1.97	1.00	1.50	1.49	1.49
Quadratic mesh ($r=2$)	2.01	3.14	3.94	3.97	1.00	2.12	3.03	3.48
Cubic mesh ($r=3$)	2.04	2.45	3.44	4.04	1.02	1.47	2.42	3.46

 Table 3: Convergence order of $\|u - u_h^\ell\|_{L^2(\Omega)}$ and $\|\nabla(u - u_h^\ell)\|_{L^2(\Omega)}$

The interpretation of the convergence rates for the bulk errors in table 3 is less straightforward. The figures in table 3 led us to the following conjecture of the error estimations on Ω , which are not always satisfied in practice: $\|u - u_h^\ell\|_{L^2(\Omega)} = O(h^{k+1} + h^{r+1})$, and $\|\nabla(u - u_h^\ell)\|_{L^2(\Omega)} = O(h^k + h^{r+1/2})$. Let us discuss every case aside. On the affine mesh, the conjecture is satisfied. The quadratic mesh acts as if r is taken as 3 instead of 2, as a consequence of the super convergence. Here, the conjecture is satisfied. On the cubic mesh, for the \mathbb{P}^2 and \mathbb{P}^3 cases (red figures in table 3), there is a default of $1/2$ compared to the conjecture. Even-though, the saturation of the convergence rate agrees with the conjecture (see \mathbb{P}^4 case).

This behavior differs from (10) for the gradient norm where h^{r+1} is now replaced by $h^{r+1/2}$. This difference could be understood from a theoretical point of view following ideas that should be presented in forthcoming works. Recall that this lift is a modification of the one defined in [7]. Using the lift given in [7], a saturation of the convergence rate is observed as follow: 2.5 for the $L^2(\Omega)$ norm and 1.5 for the gradient $L^2(\Omega)$ norm, for the quadratic and cubic meshes. These results are discussed in details in an upcoming work and expose the benefit of the new lift, defined in this paper.

Conclusion

We have presented an approach in order to numerically solve the Ventcel problem (1) and have used the code Cumin [13] to give a numerical exploration of the *a priori* errors using high order finite elements on curved meshes. This numerical analysis is supported by an alternative definition of a lift operator as compared to [7] which improved our numerical results. Beyond difficulties related to the lift definition, and beyond unexplained super convergence associated to quadratic meshes, we formulate the following conjecture for the Ventcel problem *a priori* numerical errors, the proof of which is detailed in an upcoming work.

Conjecture. Let $u \in H^{k+1}(\Omega, \Gamma)$ be a solution of the variational problem (2), let $\mathcal{T}_h^{(r)}$ be a mesh of Ω with geometrical degree r , let V_h , defined in (8), be the associated finite element

space of degree k . Then the numerical solution $u_h \in V_h$ to the discrete problem (9) satisfies,

$$\begin{aligned} \|u - u_h^\ell\|_{L^2(\Omega)} &= O(h^{k+1} + h^{r+1}), & \|\nabla(u - u_h^\ell)\|_{L^2(\Omega)} &= O(h^k + h^{r+1/2}), \\ \|u - u_h^\ell\|_{L^2(\Gamma)} &= O(h^{k+1} + h^{r+1}), & \text{and } \|\nabla_\Gamma(u - u_h^\ell)\|_{L^2(\Gamma)} &= O(h^k + h^{r+1}). \end{aligned}$$

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