# UNIQUENESS OF STRONG SOLUTIONS TO DOUBLY NONLINEAR EVOLUTION EQUATIONS 

## Jochen Merker


#### Abstract

In this article uniqueness of strong solutions to the abstract doubly nonlinear evolution equation $$
\frac{\partial B u}{\partial t}+A u=f
$$ is discussed under the main assumptions that $B^{-1}$ is strongly monotone and there is a $C<\infty$ such that $\Phi_{A}+C \Phi_{B}$ is convex for the potentials $\Phi_{A}$ resp. $\Phi_{B}$ of $A$ resp. $B$.

Keywords: Doubly nonlinear evolution equations, strong solutions, uniqueness. AMS classification: 35K90, 47J35, 34G20, 35A02.


## §1. Introduction

The aim of this article is to discuss strong solutions of abstract doubly nonlinear evolution equations

$$
\begin{equation*}
\frac{\partial B u}{\partial t}+A u=f \tag{1}
\end{equation*}
$$

and especially the uniqueness of strong solutions to an initial value. Hereby, $A: X \rightarrow X^{*}$ resp. $B: Y \rightarrow Y^{*}$ are operators on Banach spaces $X$ resp. $Y$ with a dense and separable intersection, and $f$ is an inhomogeneity or nonlinearity.

Uniqueness of weak solutions to initial data with finite energy has been established for the concrete case of a degenerate elliptic-parabolic equation

$$
\begin{equation*}
\frac{\partial b(u)}{\partial t}+\operatorname{div}(a(b(u), \nabla u))=f \tag{2}
\end{equation*}
$$

by [11] via an $L^{1}$-contraction principle for $b(u)$. Uniqueness of entropy solutions to $L^{1}$-initial data has been shown by [3] (even in presence of transport terms and therefore for degenerate elliptic-parabolic-hyperbolic equations), and uniqueness of renormalized solutions has been proved by [4]. In literature uniqueness is also discussed for several variants of (2) like the anisotropic case ([9]), the so-called triply nonlinear case ([1]) or the case of variable exponents ([2]). All these articles have in common that uniqueness is proved via Kruzhkov's method of doubling the variables.

In this article, an elementary proof of the uniqueness of strong solutions to the abstract problem (1) along the lines of [7,5,6] is given, see also [12, Section 8.5 and 11.2.3]. While a discussion of the abstract problem is more general than a discussion of the concrete equation (2) (e.g. parts of $B$ could be fractional derivatives or general convolution operators), it is a
major restriction to prove uniqueness only for strong solutions and not for weak, entropy or renormalized solutions, because in general strong solutions may not exist. However, this is the price to pay for applying an elementary method instead of a more sophisticated method like Kruzhkov's doubling of variables.

### 1.1. Outline

In Section 2 existence of strong solutions to (1) is established for initial values $u_{0} \in X \cap Y$ under the main additional assumption that

$$
\begin{equation*}
\left\langle v^{*}, d B^{-1}\left(u^{*}\right) v^{*}\right\rangle \geq c\left\|v^{*}\right\|_{H^{*}}^{2} \tag{3}
\end{equation*}
$$

holds for all $u^{*}, v^{*} \in Y^{*}$ with a constant $c>0$, where $X \cap Y \subset H \subset Y$ is an interpolation triple with a Hilbert space $H$. This assumption is equivalent to strong monotonicity of $B^{-1}$ as an operator $B^{-1}: Y^{*} \subset H^{*} \rightarrow H$. Note that there are also other situations which allow to prove the existence of certain types of strong solutions (see [10]), but here we concentrate on this situation.

For the concrete equation (2) existence of strong solutions can be guaranteed for regular initial data and potential $a=d \phi_{a}$, if $b$ is not only assumed to be nondecreasing, but additionally $b^{-1}$ is assumed to be differentiable with a nonvanishing derivative at 0 . Thus, $b$ must not be degenerate or singular at 0 , but is still allowed to grow nonlinearly.

Uniqueness of strong solutions is shown in section 3 under the convexity assumption that there is a $C<\infty$ such that $\Phi_{A}+C \Phi_{B}$ is convex for the potentials $\Phi_{A}$ resp. $\Phi_{B}$ of $A$ resp. $B$. Further, continuous dependence of strong solutions on the initial value and on the right hand side is established within this abstract framework. However, before we start our discussion let us mention two examples which illustrate that in general neither $u$ nor $B u$ need to be unique.

### 1.2. Examples for non-uniqueness

The following examples illustrate in which way weak solutions of a doubly nonlinear reaction diffusion equation (2) to an initial value may not be unique.

Example 1. Let $A: W^{1,2}(\Omega) \rightarrow\left(W^{1,2}(\Omega)\right)^{*}$ be the negative of the one-dimensional Laplacian on the interval $\Omega:=(0,1)$ under Neumann-boundary conditions $\partial u / \partial x=0$ on $\partial \Omega$, and let $B: L^{2}(\Omega) \rightarrow L^{2}(\Omega)$ be the superposition operator $(B u)(x):=b(u(x))$ induced by

$$
b(u):= \begin{cases}u+1, & \text { if } u \leq-1 \\ 0, & \text { if }-1 \leq u \leq 1 \\ u-1, & \text { if } u \geq 1\end{cases}
$$

Obviously, $B$ is a monotone potential operator, which is coercive, bounded and continuous. However, the equation $\partial B u / \partial t+A u=0$ does not have a unique solution $u$ to the zero function as initial value of $B u$. In fact, if $u(t, x)$ is an arbirary continuous function independent of $x$ which attains values between -1 and 1 , then $A u(t)=0$ and $B u(t)=0$ for every $t$. Thus, there are many weak solution $u$ to the the initial value 0 of $B u$.

Non-uniqueness of $u$ may not be considered as a problem if at least $B u$ is unique. However, in general it may even happen that $B u$ is not unique, as the following example shows, where $B$ is multivalued (so that $B^{-1}$ is not strictly monotone), see also [8, Remark 4].

Example 2. Let $\Omega:=(0,1)$, let $B: L^{2}(\Omega) \rightarrow L^{2}(\Omega)$ be the superposition operator induced by the multivalued mapping

$$
b(u):= \begin{cases}u-1, & \text { if } u<0 \\ {[-1,1],} & \text { if } u=0 \\ u+1, & \text { if } u>0\end{cases}
$$

and let $A: W_{0}^{1,2}(\Omega) \rightarrow\left(W_{0}^{1,2}(\Omega)\right)^{*}$ be the operator $\langle A u, w\rangle=\int_{\Omega} u_{x} w_{x}+b(u) w_{x} d x$, i.e. $A u=$ $-u_{x x}-v_{x}$ on smooth functions with $v(t, x) \in b(u(t, x))$ under Dirichlet conditions $u=0$ on $\partial \Omega$. Then one solution to the initial value 1 of $B u$ is given by $u:=0$ and $v:=1 \in B u$, but for every $C \geq 1$ and every $C^{1}$-function $h$ on $[0, \infty)$ with values between 0 and 2 also $u:=0$ and

$$
v(t, x):= \begin{cases}1, & \text { if } 0 \leq t+x \leq C, \\ 1-h(t+x-C), & \text { if } t+x \geq C,\end{cases}
$$

define a solution with $v(0)=1$ due to $v_{t}-v_{x}=0\left(\right.$ and $\left.u_{x x}=0\right)$.

## §2. Existence of strong solutions

In this section the existence of strong solutions to the abstract equation (1) is discussed by energy methods for the case that $B^{-1}$ exists and is strongly monotone as an operator on some intermediate Hilbert space. However, first let us formulate standard structural assumptions which allow to prove existence of weak solutions to (1) :
(A1) $X$ and $Y$ are reflexive Banach spaces with a dense and separable intersection $X \cap Y^{1}$, which is compactly embedded into $Y$.
(A2) $B: Y \rightarrow Y^{*}$ is a continuous strictly monotone potential operator, which is coercive and satisfies the growth condition $\|B u\|_{Y^{*}} \leq C\left(1+\|u\|_{Y}^{m-1}\right)$ with a constant $C<\infty$ and a parameter $1<m<\infty$.
(A3) $A: X \rightarrow X^{*}$ is a pseudomonotone operator, which satisfies the semicoercivity condition $\langle A u, u\rangle \geq c_{1}\|u\|_{X}^{p}-c_{2}\|u\|_{X}-c_{3}\|B u\|_{Y^{*}}^{m^{\prime}}$ and has growth $\|A u\|_{X^{*}} \leq C\left(\|u\|_{Y}\right)\left(1+\|u\|_{X}^{p-1}\right)$ for a parameter $1<p<\infty$ with constants $c_{1}>0, c_{2}, c_{3}$ and an increasing function $C: \mathbb{R}_{0}^{+} \rightarrow \mathbb{R}_{0}^{+}$.
If $f \in L^{p^{\prime}}\left(0, T ; X^{*}\right)+L^{1}\left(0, T ; Y^{*}\right)$ is an inhomogeneity, then under the assumptions (A1)-(A3) a weak solution $u$ exists to an initial value $u_{0} \in Y$ in the sense that $u \in L^{p}(0, T ; X) \cap L^{\infty}(0, T ; Y)$ is such that $B u \in L^{\infty}\left(0, T ; Y^{*}\right)$ has the initial value $B u_{0} \in Y^{*}$ and a weak derivative $\partial B u / \partial t \in$ $L^{p^{\prime}}\left(0, T ; X^{*}\right)+L^{1}\left(0, T ; Y^{*}\right)$ satisfying (1) as an equation in $(X \cap Y)^{*}$ for a.e. $t \in(0, T)$, or equivalently as an equation in $L^{p^{\prime}}\left(0, T ; X^{*}\right)+L^{1}\left(0, T ; Y^{*}\right)$.

[^0]Here we are interested in a slightly different case, where the inhomogeneity $f$ satisfies $f \in L^{p^{\prime}}\left(0, T ; X^{*}\right)+L^{2}\left(0, T ; H^{*}\right)$ for an intermediate Hilbert space $H$ of the inclusion $X \cap Y \subset Y$ given by (A1). More precisley, we require that $X \cap Y \subset H \subset Y$ is an interpolation triple, i.e. there is a $\theta \in[0,1]$ and a constant $C<\infty$ such that $\|u\|_{H} \leq C\|u\|_{X}^{\theta}\|u\|_{Y}^{1-\theta}$ for every $u \in X \cap Y$. In this case, under the additional assumptions that $B$ satisfies the coercivity condition $\|u\|_{Y} \leq C\left(1+\|B u\|_{Y^{*}}^{m^{\prime}}\right)$ with a constant $C<\infty$ and $p \geq 2$ or $1 / 2 \leq \theta \leq p / 2$ hold, there exists a weak solution of (1) in the following sense:
Definition 1. A function $u \in L^{p}(0, T ; X) \cap L^{\infty}(0, T ; Y)$ is called a weak solution of equation (1) to the initial value $u_{0} \in Y$, if $B u \in L^{\infty}\left(0, T ; Y^{*}\right)$ has the initial value $B u_{0} \in Y^{*}$ and a weak derivative $\partial B u / \partial t \in L^{p^{\prime}}\left(0, T ; X^{*}\right)+L^{2}\left(0, T ; H^{*}\right)$ satisfying equation (1) as an equation in $(X \cap H)^{*}$ for a.e. $t \in(0, T)$, or equivalently as an equation in $L^{p^{\prime}}\left(0, T ; X^{*}\right)+L^{2}\left(0, T ; H^{*}\right)$.

The existence of weak solutions in the sense of Definition 1 can even be generalised to the case where $f=f(t, u)$ is a nonlinearity. In fact, if $B$ satisfies the stronger coercivity condition $\|u\|_{Y} \leq C\left(1+\|B u\|_{Y^{*}}^{m^{\prime}-1}\right)$ with a constant $C<\infty$ and $f=f(t, u)$ is a nonlinearity which satisfies the growth condition $\|f(t, u)\|_{H *} \leq C\left(\gamma(t)+\|u\|_{Y}^{(m-1)(1-\theta)}\right)$ with a constant $C<\infty$ and a function $\gamma \in L^{2}(0, T)$, then there still exist weak solutions in the sense of Definition 1.

Now we are interested in assumptions, which guarantee that weak solutions even have better properties than those mentioned in Definition 1. The following theorem formulates such assumptions in the special case that $B^{-1}: Y^{*} \subset H^{*} \rightarrow H$ is strongly monotone, see [10].
Theorem 1. Additionally to the structural assumptions (A1)-(A3) assume that $H$ is a Hilbert space such that $X \cap Y \subset H \subset Y$ is an interpolation triple and $p \geq 2$ or $1 / 2 \leq \theta \leq p / 2$ hold. Further, assume that

- $B^{-1}: Y^{*} \rightarrow Y$ is $C^{1}$, satisfies $\|u\|_{Y} \leq C\left(1+\|B u\|_{Y^{*}}^{m^{\prime}-1}\right)$ with a constant $C<\infty$, and is strongly monotone in the sense that $\left\langle v^{*}, d B^{-1}\left(u^{*}\right) v^{*}\right\rangle \geq c\left\|v^{*}\right\|_{H^{*}}^{2}$ for all $u^{*}, v^{*} \in Y^{*}$ with a constant $c>0^{2}$,
- $A: X \rightarrow X^{*}$ is a potential operator such that the intersection of $Y$ and the domain $D(A):=\left\{u \in X \mid A u \in H^{*}\right\}$ of $A$ w.r.t. $H^{*}$ is dense in $X \cap Y$,
- $f$ is an inhomogeneity in $L^{2}\left(0, T ; H^{*}\right)$ or a nonlinearity $f=f(t, u)$ such that $g(t, u):=$ $d B^{-1}(B u)^{*} f(t, u)$ satisfies the growth condition $\|g(t, u)\|_{H} \leq C\left(\gamma(t)+\|u\|_{Y}^{(m-1)(1-\theta)}\right)$ with a constant $C<\infty$ and a function $\gamma \in L^{2}(0, T)$.
Then there exists to every initial value $u_{0} \in X \cap Y$ a strong solution $u$ of equation (1) in the sense that $u$ is a weak solution which additionally satisfies $u \in L^{\infty}(0, T ; X)$, and $B u \in$ $L^{\infty}\left(0, T ; Y^{*}\right)$ and a weak derivative $\partial B u / \partial t \in L^{2}\left(0, T ; H^{*}\right)$.

Let us shortly sketch the proof of this theorem given in [10].
Proof. Use a Faedo-Galerkin method and consider the restrictions

$$
\begin{equation*}
\frac{\partial B_{k} u_{k}}{\partial t}+A_{k} u_{k}=f_{k} \tag{4}
\end{equation*}
$$

of equation (1) to an increasing sequence of finite-dimensional subspaces $W_{k} \subset D(A) \cap Y \subset$ $X \cap Y$, where $A_{k}, B_{k}$ are the restrictions of $A, B$ to $W_{k}$ and $f_{k}$ is a continuous approximation

[^1]of $f$ with values in $W_{k}$. Due to (A1)-(A3) short-time existence of solutions $u_{k}$ of this ODE to initial values $u_{0 k} \in W_{k}$ can be guaranteed. Test (4) by $u_{k}$ to obtain from the semicoercivity condition on $A$ the a priori estimate
\[

$$
\begin{aligned}
& \hat{\Phi}_{B}\left(u_{k}(t)\right)+\left(c_{1}-\frac{\epsilon^{p}}{p}\right) \int_{0}^{T}\left\|u_{k}(s)\right\|_{X}^{p} d s \\
& \quad \leq \hat{\Phi}_{B}\left(u_{0 k}\right)+\frac{1}{p^{\prime} \epsilon^{p^{\prime}}}\left|c_{2}\right|^{p^{\prime}} T+\int_{0}^{t} c_{3}\left\|B_{k} u_{k}(s)\right\|_{Y^{*}}^{n^{\prime}} d s+\int_{0}^{t}\left\|f_{k}(s)\right\|_{H^{*}}\|u\|_{H} d s
\end{aligned}
$$
\]

where $\hat{\Phi}_{B}(u)=\Phi_{B}^{*}(B u)$ denotes the Legendre transform of the convex potential $\Phi_{B}$ of $B$ in dependence of $B u, \epsilon>0$ is sufficiently small and the energy identity $\frac{d}{d t} \hat{\Phi}_{B}(u)=\left\langle\frac{\partial B u}{\partial t}, u\right\rangle$ was used. As a consequence of the growth condition $\|B u\|_{Y^{*}} \leq C\left(1+\|u\|_{Y}^{m-1}\right)$ we have $\|B u\|_{Y^{*}}^{n^{\prime}} \leq C\left(1+\hat{\Phi}_{B}(u)\right)$, as a consequence of the coercivity condition $\|u\|_{Y} \leq C\left(1+\|B u\|_{Y^{*}}^{n^{\prime}}\right)$ we have $\|u\|_{Y} \leq C\left(1+\hat{\Phi}_{B}(u)\right)$, and the assumptions $p \geq 2$ or $1 / 2 \leq \theta \leq p / 2$ allow to estimate the last term by $C \int_{0}^{t}\left(1+\hat{\Phi}_{B}(u)\right) d s$ in the case that $f \in L^{2}\left(0, T ; H^{*}\right)$ is an inhomogeneity. In the case that $f=f(t, u)$ is a nonlinearity apply inequality (3) to $u^{*}:=B u, v^{*}:=f(t, u)$, to obtain

$$
c\|f(t, u)\|_{H^{*}}^{2} \leq\left\langle f(t, u), d B^{-1}(B u) f(t, u)\right\rangle=\langle f(t, u), g(t, u)\rangle \leq\|f(t, u)\|_{H^{*}}\|g(t, u)\|_{H}
$$

so that by the assumptions on $g$ the growth condition

$$
\|f(t, u)\|_{H^{*}} \leq \frac{1}{c}\|g(t, u)\|_{H} \leq \frac{C}{c}\left(\gamma(t)+\|u\|_{Y}^{(m-1)(1-\theta)}\right)
$$

is valid and the last term can again be estimated by $C \int_{0}^{t}\left(1+\hat{\Phi}_{B}(u)\right) d s$. Thus, Gronwall's lemma allows to deduce uniform bounds w.r.t. $k$ of $u_{k}$ in $L^{\infty}(0, T ; Y) \cap L^{p}(0, T ; X), B u_{k}$ in $L^{\infty}\left(0, T ; Y^{*}\right)$ and $A u_{k}$ in $L^{p^{\prime}}\left(0, T ; X^{*}\right)$. Due to these bounds a weakly convergent subsequence $u_{k} \rightharpoonup u$ can be extracted. Finally, time-compactness and pseudomonotonicity allow to conclude that $u$ is a weak solution of (1).

To obtain a strong solution we would like to test the approximate equation (4) by $\partial u_{k} / \partial t$, but (4) only guarantees the existence of $\partial B_{k} u_{k} / \partial t \in C\left(0, T ; W^{*}\right)$ and not the existence of $\partial u_{k} / \partial t$. However, as $B^{-1}$ is assumed to be continuously differentiable, the chain rule implies the existence of

$$
\begin{equation*}
\frac{\partial u}{\partial t}=d B^{-1}(B u) \frac{\partial B u}{\partial t} \tag{5}
\end{equation*}
$$

Due to $W_{k} \subset D(A)$ and $f_{k} \in L^{2}\left(0, T ; H^{*}\right)$ a solution $u_{k} \in C^{1}\left(0, T ; W_{k}\right)$ of the approximate equation (4) satisfies $\partial B_{k} u_{k} / \partial t \in H^{*}$ for a.e. $t$. Especially, inequality (3) can be applied to $u^{*}:=B u_{k}(t), v^{*}=\partial B u_{k}(t) / \partial t$, to obtain

$$
\left\langle\frac{\partial B_{k} u_{k}}{\partial t}, \frac{\partial u_{k}}{\partial t}\right\rangle \geq c\left\|\frac{\partial B u_{k}}{\partial t}\right\|_{H^{*}}^{2} .
$$

Further, as $g(t, u):=d B^{-1}(B u)^{*} f(t, u)$ satisfies $\|g(t, u)\|_{H} \leq C\left(\gamma(t)+\|u\|_{Y}^{(m-1)(1-\theta)}\right)$ with a constant $C<\infty$ and a function $\gamma \in L^{2}(0, T)$, and as a uniform bound of $u_{k}$ in $L^{\infty}(0, T ; Y)$
w.r.t. $k$ has already been established, we can conclude that $g\left(\cdot, u_{k}(\cdot)\right)$ is uniformly bounded in $L^{2}(0, T ; H)$. Thus, a test of (4) by $\partial u_{k} / \partial t$ yields

$$
\left(c-\frac{\epsilon^{2}}{2}\right)\left\|\frac{\partial B u_{k}}{\partial t}\right\|_{H^{*}}^{2}+\frac{d}{d t} \Phi_{A}\left(u_{k}\right) \leq \frac{1}{2 \epsilon^{2}}\left\|g\left(\cdot, u_{k}(\cdot)\right)\right\|_{H}^{2} \leq C
$$

with a constant $C<\infty$ for sufficiently small $\epsilon>0$. Using this differential inequality uniform a priori estimates w.r.t. $k$ of $\partial B u_{k} / \partial t$ in $L^{2}\left(0, T ; H^{*}\right)$ and $u_{k}$ in $L^{\infty}(0, T ; X)$ can be established. Therefore, additionally we are able to guarantee weak ${ }^{*}$ convergence of a subsequence of the approximate solutions $u_{k}$ in $L^{\infty}(0, T ; X)$ and weak convergence of $\partial B u_{k} / \partial t$ in $L^{2}\left(0, T ; H^{*}\right)$, It is simple to verify that the weak limits of these sequences are identical with their expected values $u$ and $\partial B u / \partial t$, hence the proof of Theorem 1 is finished.

As a consequence of Theorem 1 we have $B u \in W^{1,2}\left(0, T ; H^{*}\right) \subset C\left(0, T ; H^{*}\right)$ for strong solutions due to $B u \in L^{\infty}\left(0, T ; Y^{*}\right) \subset L^{2}\left(0, T ; H^{*}\right)$ and $\partial B u / \partial t \in L^{2}\left(0, T ; H^{*}\right)$. Further, as $\partial B u / \partial t$ and $f$ lie in $L^{2}\left(0, T ; H^{*}\right)$, also $A u=f-\partial B u / \partial t$ lies in $L^{2}\left(0, T ; H^{*}\right)$. Therefore, equation (1) holds as an equation in $H^{*}$ for a.e. $t \in[0, T]$, and thus $u(t) \in D(A)$ for a.e. $t \in[0, T]$. Let us explicitly mention this observation as a corollary.
Corollary 2. Under the assumptions of Theorem 1 the relation $A u \in L^{2}\left(0, T ; H^{*}\right)$ holds for $a$ strong solution $u$, and equation (1) is valid as an equation in $H^{*}$ for a.e. $t \in(0, T)$.

The following example shows how Theorem 1 can be applied to the concrete problem (2).
Example 3. Let $\Omega \subset \mathbb{R}^{n}$ be a bounded domain and let $1<m<2$. Consider the space $Y:=L^{m}(\Omega)$ so that $H:=L^{2}(\Omega)$ is continuously embedded into $Y$. Assume that $\phi_{b}: \mathbb{R} \rightarrow \mathbb{R}$ is a convex function which behaves like $\left(C_{1} / 2\right)|u|^{2}+o\left(|u|^{2}\right)$ as $|u| \rightarrow 0$ and like $\left(C_{2} / m\right)|u|^{m}+\omega\left(|u|^{m}\right)$ as $|u| \rightarrow \infty$. Denote by $b:=d \phi_{b}$ the derivative of $\phi_{b}$ and by $B: Y \rightarrow Y^{*}$ the corresponding superposition operator. Then $b^{-1}(u)$ behaves like $C_{1}^{-1} u$ as $|u| \rightarrow 0$ and like $C_{2}^{1-m^{\prime}}|u|^{m^{\prime}-2} u$ as $|u| \rightarrow \infty$, so that $\left(b^{-1}\right)^{\prime}(u)$ behaves like $C_{1}^{-1}$ as $|u| \rightarrow 0$ and like $\left(m^{\prime}-1\right) C_{2}^{1-m^{\prime}}|u|^{((2-m) /(m-1))}$ as $|u| \rightarrow \infty$. Especially, pointwisely $\left(b^{-1}\right)^{\prime}(u) \geq c$ for a constant $c>0$ so that

$$
c\left\|v^{*}\right\|_{2}^{2}=\int_{\Omega} c\left|v^{*}\right|^{2} d x \leq \int_{\Omega}\left(b^{-1}\right)^{\prime}\left(u^{*}\right)\left|v^{*}\right|^{2} d x
$$

and as a consequence

$$
\left\langle v^{*}, d B^{-1}\left(u^{*}\right) v^{*}\right\rangle \geq c\left\|v^{*}\right\|_{2}^{2}
$$

for all $u^{*}, v^{*} \in Y^{*}$, i.e. inequality (3) is valid. Note that although $b$ is not degenerate or singular at $u=0$, the operator $B$ can not be realized as an operator on $H$ as $b$ grows like $C|u|^{m-1}$ as $|u| \rightarrow \infty$. Thus (2) is not degenerate or singular at $u=0$, but still should be considered as an equation for $u \in Y$ and not for $u \in H$.

Finally, assume that $a$ has a $p$-coercive potential, $1<p<\infty$, e.g. $a(\nabla u)=|\nabla u|^{p-2} \nabla u$, and consider the corresponding operator $A: W_{0}^{1, p}(\Omega) \rightarrow\left(W_{0}^{1, p}(\Omega)\right)^{*},\langle A u, v\rangle:=\int_{\Omega} a(\nabla u) \cdot \nabla u d x$, so that (2) is solved under Dirichlet boundary conditions. For this choice $X:=W_{0}^{1, p}(\Omega)$, and $m<p^{*}$ has to be required to have a compact embedding $X \cap Y \subset Y$. Now Gagliardo-Nirenberg inequalities

$$
\|u\|_{L^{2}} \leq\|\nabla u\|_{L^{p^{*}}}^{\theta}\|u\|_{L^{m}}^{1-\theta}
$$

are valid for $1 / 2=\theta / p^{*}+(1-\theta) / m, 1 / p^{*} \leq 1 / 2$, where the parameter $\theta$ of the interpolation triple $X \cap Y \subset H \subset Y$ is given by $\theta=\left((2-m) p^{*}\right) /\left(2\left(p^{*}-m\right)\right)$. Especially, in the case $p<2$ the inequality $1 / 2 \leq \theta \leq p / 2$ is valid iff $\left((2-p) p^{*}\right) /\left(p^{*}-p\right) \leq m \leq p^{*} /\left(p^{*}-1\right)$. For example, if $n=3$ and $p$ is slightly smaller than 2 , then already $m<6 / 5$ has to be required.

Further, the right hand side $f$ of (2) and $g:=d B^{-1}(B u)^{*} f(u)$ are related by

$$
\begin{equation*}
f(t, x, u)=\frac{g(t, x, u)}{\left(b^{-1}\right)^{\prime}(u)}, \tag{6}
\end{equation*}
$$

where $\left(b^{-1}\right)^{\prime}$ is bounded away from zero. Thus, if $g(t, x, u)$ is a pregiven nonlinearity such that $|g(t, x, u)| \leq C\left(\gamma(t, x)+|u|^{(m-1)(1-\theta)}\right)$, then by (6) a corresponding right hand side $f$ can be defined such that the assumptions of Theorem 1 are satisfied. Thus, under the former conditions there exists a strong solution of (2) to initial values $u_{0} \in W_{0}^{1, p}(\Omega) \cap L^{m}(\Omega)$.

Finally, it can be shown that inhomogeneities

$$
f \in L^{2\left(\left(m(m-1)^{2}\left(p^{*}-2\right)\right) /\left(2(2-m)\left(p^{*}-m\right)\right)\right)^{\prime}}\left(0, T ; L^{(2 m(m-1)) /\left((m+1 / 2)^{2}-17 / 4\right)}(\Omega)\right)
$$

can be represented via (6) by a function $g(t, x, u)=f(t, x)\left(b^{-1}\right)^{\prime}(u)$ satisfying the growth condition provided that

$$
\frac{\sqrt{17}-1}{2}<m \leq 2 \quad \text { and } \quad p^{*}>\frac{2 m\left(m^{2}-m-1\right)}{m^{3}-2 m^{2}+3 m-4}
$$

in the case $p<n$.

## §3. Uniqueness of strong solutions

Under the assumptions of Theorem 1 equation (1) admits a strong solution to an initial value $u_{0} \in X \cap Y$ in the sense that $u \in L^{\infty}(0, T ; X \cap Y)$ is a weak solution such that $B u \in L^{\infty}\left(0, T ; Y^{*}\right)$ has a weak derivative $\partial B u / \partial t \in L^{2}\left(0, T ; H^{*}\right)$, and especially $A u \in L^{2}\left(0, T ; H^{*}\right)$. The following theorem guarantees uniqueness of strong solutions and continuous dependence on the initial value and the right hand side.
Theorem 3. Additionally to the assumptions of Theorem 1 suppose that there is a constant $C<\infty$ such that

$$
\begin{gather*}
\langle A u-A v, u-v\rangle+C\langle B u-B v, u-v\rangle \geq 0 \text { for all } u, v \in X \cap Y \text { and }  \tag{7}\\
\left\langle B u-B v, d B^{-1}(B u) A u-d B^{-1}(B v) A v\right\rangle+C\langle B u-B v, u-v\rangle \geq 0 \text { for all } u, v \in D(A) \cap Y, \tag{8}
\end{gather*}
$$

where $D(A)=\left\{u \in X \mid A u \in H^{*}\right\}$ denotes the domain of $A$ w.r.t. $H^{*}$. Then the following statements are valid:

- If $f=0$, then strong solutions of equation (1) are unique.
- If $f \in L^{1}\left(0, T ; Y^{*}\right)$ and $d B^{-1}: Y^{*} \subset H \rightarrow L\left(Y^{*}, H\right)$ is Lipschitz continuous, then strong solutions of equation (1) are unique and $Y \ni u_{0} \mapsto B u \in C\left(0, T ; H^{*}\right)$ is continuous.
- If $d B^{-1}$ and $B^{-1}$ are Lipschitz continuous, then $Y \times L^{1}\left(0, T ; Y^{*}\right) \ni\left(u_{0}, f\right) \mapsto B u \in$ $C\left(0, T ; H^{*}\right)$ is continuous.

Remark 1. Note that inequality (7) is equivalent to the convexity of $\Phi_{A}+C \Phi_{B}$ on $X \cap Y$, while inequality (8) is equivalent to the convexity of $\Phi_{A} \circ B^{-1}+C \Phi_{B}^{*}$ on $B(D(A) \cap Y)$, where $\Phi_{B}^{*}$ is the Legendre transform of $\Phi_{B}$ and hence a potential of $B^{-1}$.

Proof. Assume that $u, v$ are strong solutions of

$$
\frac{\partial B u}{\partial t}+A u=f_{1} \quad \text { resp. } \quad \frac{\partial B v}{\partial t}+A v=f_{2}
$$

To prove uniqueness, test the difference of these equations by $u-v$ and integrate the resulting equation over $[0, t]$ to obtain

$$
\int_{0}^{t}\left\langle\frac{\partial}{\partial s}(B u-B v), u-v\right\rangle d s+\int_{0}^{t}\langle A u-A v, u-v\rangle d s=\int_{0}^{t}\left\langle f_{1}-f_{2}, u-v\right\rangle d s
$$

Now

$$
\left\langle\frac{\partial}{\partial s}(B u-B v), u-v\right\rangle=\frac{d}{d t}\langle B u-B v, u-v\rangle-\left\langle B u-B v, \frac{\partial}{\partial s}(u-v)\right\rangle
$$

and thus

$$
\begin{aligned}
\int_{0}^{t}\left\langle\frac{\partial}{\partial s}(B u-B v), u-v\right\rangle d s= & (\langle B u-B v, u-v\rangle)(t)-(\langle B u-B v, u-v\rangle)(0) \\
& -\int_{0}^{t}\left\langle B u-B v, d B^{-1}(B u)\left(f_{1}-A u\right)-d B^{-1}(B v)\left(f_{2}-A v\right)\right\rangle d s
\end{aligned}
$$

due to $\partial u / \partial t=d B^{-1}(B u) \partial B u / \partial t=d B^{-1}(B u)\left(f_{1}-A u\right)$ and similar for $v$. Hence, if $f_{1}=0=f_{2}$, then

$$
\begin{aligned}
& (\langle B u-B v, u-v\rangle)(t) \\
& =(\langle B u-B v, u-v\rangle)(0)-\int_{0}^{t}\langle A u-A v, u-v\rangle d s-\int_{0}^{t}\left\langle B u-B v, d B^{-1}(u) A u-d B^{-1}(v) A v\right\rangle d s \\
& \leq(\langle B u-B v, u-v\rangle)(0)+2 C \int_{0}^{t}\langle B u-B v, u-v\rangle d s
\end{aligned}
$$

due to the assumptions (7) and (8). By Gronwall's lemma

$$
(\langle B u-B v, u-v\rangle)(t) \leq(\langle B u-B v, u-v\rangle)(0) \exp (2 C t),
$$

so that $u(0)=v(0)$ implies $(\langle B u-B v, u-v\rangle)(t)=0$ for a.e. $t \in[0, T]$ and hence $u=v$ by strict monotonicity of $B$.

If $f_{1}=f_{2}=: f \in L^{1}\left(0, T ; Y^{*}\right)$, then
$(\langle B u-B v, u-v\rangle)(t)$
$=(\langle B u-B v, u-v\rangle)(0)-\int_{0}^{t}\langle A u-A v, u-v\rangle d s$
$-\int_{0}^{t}\left\langle B u-B v, d B^{-1}(u) A u-d B^{-1}(v) A v\right\rangle d s+\int_{0}^{t}\left\langle B u-B v,\left(d B^{-1}(B u)-d B^{-1}(B v)\right) f\right\rangle d s$
$\leq(\langle B u-B v, u-v\rangle)(0)+2 C \int_{0}^{t}\langle B u-B v, u-v\rangle d s+M \int_{0}^{t}\|B u-B v\|_{H^{*}}^{2}\|f\|_{Y^{*}} d s$
with the Lipschitz constant $M$ of $d B^{-1}: Y^{*} \subset H^{*} \rightarrow L\left(Y^{*}, H\right)$. By strong monotonicity of $B^{-1}: Y^{*} \subset H^{*} \rightarrow H$ the inequality $\|B u-B v\|_{H^{*}}^{2} \leq c^{-1}\langle B u-B v, u-v\rangle$ is valid, hence by Gronwall's lemma

$$
(\langle B u-B v, u-v\rangle)(t) \leq(\langle B u-B v, u-v\rangle)(0) \exp \left(2 C T+\frac{M}{c} \int_{0}^{T}\|f\|_{Y^{*}} d s\right)
$$

Especially, again by strong monotonicity of $B^{-1}$

$$
c\|B u(t)-B v(t)\|_{H^{*}}^{2} \leq\|B u(0)-B v(0)\|_{Y^{*}}\|u(0)-v(0)\|_{Y} \exp \left(2 C T+\frac{M}{c} \int_{0}^{T}\|f\|_{Y^{*}} d s\right),
$$

so that $Y \ni u(0) \mapsto B u \in C\left(0, T ; H^{*}\right)$ is continuous.
Finally, if $f_{1}, f_{2} \in L^{1}\left(0, T ; Y^{*}\right)$, then the additional terms may be estimated by

$$
\int_{0}^{t}\left\langle f_{1}-f_{2}, u-v\right\rangle d s \leq \frac{L}{2} \int_{0}^{t}\left\|f_{1}-f_{2}\right\|_{Y^{*}}\left(1+\|B u-B v\|_{H^{*}}^{2}\right) d s
$$

with the Lipschitz constant $L$ of $B^{-1}: Y^{*} \subset H^{*} \rightarrow Y$ and by

$$
\begin{aligned}
& \int_{0}^{t}\left\langle B u-B v, d B^{-1}(B u) f_{1}-d B^{-1}(B v) f_{2}\right\rangle d s \\
& \quad \leq M \int_{0}^{t}\|B u-B v\|_{H^{*}}^{2}\left\|f_{1}\right\|_{Y^{*}} d s+\frac{M K}{2} \int_{0}^{t}\left(1+\|B u-B v\|_{H^{*}}^{2}\right)\left\|f_{1}-f_{2}\right\|_{Y^{*}} d s
\end{aligned}
$$

with a bound $K$ of $d B^{-1}(B v)$ in $C\left(0, T ; L\left(Y^{*}, H\right)\right)$. Thus,

$$
\begin{aligned}
(\langle B u-B v, u-v\rangle)(t) \leq & \left((\langle B u-B v, u-v\rangle)(0)+\frac{M K+L}{2} \int_{0}^{T}\left\|f_{1}-f_{2}\right\|_{Y^{*}} d s\right) \\
& \exp \left(2 C T+\frac{M}{c} \int_{0}^{T}\left\|f_{1}\right\|_{Y^{*}} d s+\frac{M K+L}{2 c} \int_{0}^{T}\left\|f_{1}-f_{2}\right\|_{Y^{*}} d s\right),
\end{aligned}
$$

and especially

$$
\begin{aligned}
c^{2}\|B u(t)-B v(t)\|_{H^{*}}^{2} \leq & \left(\|B u(0)-B v(0)\|_{Y^{*}}\|u(0)-v(0)\|_{Y}+\frac{M K+L}{2} \int_{0}^{T}\left\|f_{1}-f_{2}\right\|_{Y^{*}} d s\right) \\
& \exp \left(2 C T+\frac{M}{c} \int_{0}^{T}\left\|f_{1}\right\|_{Y^{*}} d s+\frac{M K+L}{2 c} \int_{0}^{T}\left\|f_{1}-f_{2}\right\|_{Y^{*}} d s\right),
\end{aligned}
$$

so that $Y \times L^{1}\left(0, T ; Y^{*}\right) \ni(u(0), f) \mapsto B u \in C\left(0, T ; H^{*}\right)$ is continuous.

## §4. Conclusion

In this article strong solutions to abstract doubly nonlinear evolution equations were discussed under the assumption that $B^{-1}$ is strongly monotone on some intermediate Hilbert space. In this case, strong solutions behave similar as strong solutions to nonlinear evolution equations $\partial u / \partial t+A u=f$. Particularly, under the two convexity conditions (7) and (8) it is possible to give an elementary proof of uniqueness and to obtain continuous dependence on the data. However, for degenerate resp. singular problems where merely weak solutions exist it does not seem possible to avoid more sophisticated methods like Kruzhkov's doubling of variables.

## References

[1] Andreianov, B., Bendahmane, M., Karlsen, K. H., , and Ouaro, S. Well-posedness results for triply nonlinear degenerate parabolic equations. Journal of Differential Equations 247 (2002), 277-302. doi:10.1016/j.jde.2009.03.001.
[2] Bendahmane, M., Wittbold, P., and Zimmermann, A. Renormalized solutions for a nonlinear parabolic equation with variable exponent and $L^{1}$-data. Journal of Differential Equations 249 (2010), 1483-1515. doi:10.1016/j.jde.2010.05.011.
[3] Carrillo, J. Entropy solutions for nonlinear degenerate problems. Archive for Rational Mechanics and Analysis 147 (1999), 269-361. doi:10.1007/s002050050152.
[4] Carrillo, J., and Wittbold, P. Uniqueness of renormalized solutions of degenerate elliptic-parabolic problems. Journal of Differential Equations 156 (1999), 93-121. doi:10.1006/jdeq. 1998.3597.
[5] Gajewski, H. On a variant of monotonicity and its application to differential equations. Nonlinear Analysis: Theory, Methods E Applications 22 (1994), 73-80.
[6] Gajewski, H., and Skrypnik, I. V. On the uniqueness of solutions for nonlinear ellipticparabolic equations. Journal of Evolution Equations 3 (2003), 247-281. doi:10. 1007/s00028-003-0094-y.
[7] Gröger, K., and Nečas, J. On a class of nonlinear initial-value problems in hilbert spaces. Mathematische Nachrichten 93 (1979), 21-31.
[8] Igbida, N., and Urbano, J. M. Uniqueness for nonlinear degenerate problems. Nonlinear Differential Equations and Applications 10 (2003), 287-307. doi:10.1007/ s00030-003-1030-0.
[9] Karlsen, K. H., and Ohlberger, M. A note on the uniqueness of entropy solutions of nonlinear degenerate parabolic equations. Journal of Mathematical Analysis and Applications 275 (2002), 439-458.
[10] Matas, A., and Merker, J. Strong solutions of doubly nonlinear parabolic equations. Journal for Analysis and its Applications ((accepted)).
[11] Отто, F. $L^{1}$-contraction and uniqueness for quasilinear elliptic-parabolic equations. Journal of Differential Equations 131 (1996), 20-38. doi:10.1006/jdeq. 1996. 0155.
[12] Rousíčєк, T. Nonlinear Partial Differential Equations with Applications, vol. 153 of International Series of Numerical Mathematics. Birkhäuser, Basel, 2005.

Jochen Merker
University of Rostock - Institute of Mathematics
Ulmenstr. 69 (Haus 3)
18057 Rostock
jochen.merker@uni-rostock.de


[^0]:    ${ }^{1}$ i.e. there are continuous linear embeddings of $X$ and $Y$ into a complete locally convex space $Z$ such that the intersection $X \cap Y$ within $Z$ is dense in $X$ resp. $Y$ w.r.t. the norms $\|\cdot\|_{X}$ resp. $\|\cdot\|_{Y}$, and that $X \cap Y$ is separable w.r.t. the norm $\|\cdot\|_{X}+\|\cdot\|_{Y}$.

[^1]:    ${ }^{2}$ This condition is equivalent to strong monotonicity of $B^{-1}$ as an operator $B^{-1}: Y^{*} \subset H^{*} \rightarrow H \subset Y$, i.e. to $\left\langle u^{*}-v^{*}, B^{-1} u^{*}-B^{-1} v^{*}\right\rangle \geq c\left\|u^{*}-v^{*}\right\|_{H^{*}}^{2}$ for arbitrary $u^{*}, v^{*} \in Y^{*}$ with a constant $c>0$.

