

# STOKES AND NAVIER-STOKES EQUATIONS WITH PERIODIC BOUNDARY CONDITIONS AND PRESSURE LOSS

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**Abstract.** The object of this present work is to show the existence and uniqueness results for the Stokes and Navier-Stokes equations which model the laminar flow of an incompressible fluid inside a two-dimensional plane channel with periodic sections. The data of the pressure loss coefficient in the channel enables us to establish a relation on the pressure and to thus formulate an equivalent problem.

*Keywords:* Stokes problem, Navier-Stokes equations, incompressible fluid, periodic boundary conditions, pressure loss.

## §1. Introduction

The problem which one proposes to study here is that modelling a laminar flow inside a two-dimensional plane channel with periodic section. Let  $\Omega$  be an open bounded connected lipschitzian set of  $\mathbb{R}^2$  (see figure hereafter), and its boundary  $\Gamma$  is  $\Gamma = \Gamma_0 \cup \Gamma_1 \cup \Gamma_2$ , where  $\Gamma_0 = \{0\} \times ]-1, 1[$  and  $\Gamma_1 = \{1\} \times ]-1, 1[$ . One defines the space

$$V = \left\{ \mathbf{v} \in \mathbf{H}^1(\Omega) ; \operatorname{div} \mathbf{v} = 0, \mathbf{v} = \mathbf{0} \text{ on } \Gamma_2, \mathbf{v}|_{\Gamma_0} = \mathbf{v}|_{\Gamma_1} \right\}.$$

Here, there are not external forces and viscosity is equal to 1. Thus for  $\pi \in \mathbb{R}$  given, one considers the problem

$$(\mathcal{S}) \begin{cases} \text{Find } \mathbf{u} \in V \text{ such that} \\ \forall \mathbf{v} \in V, \int_{\Omega} \nabla \mathbf{u} \cdot \nabla \mathbf{v} \, d\mathbf{x} = \pi \int_{-1}^{+1} v_1(1, y) \, dy. \end{cases}$$

## §2. Stokes problem ( $\mathcal{S}$ )

With an aim of drawing up the suitable functional framework of the problem, firstly one proposes to study the problem ( $\mathcal{S}$ ).

**Theorem 1.** *Problem ( $\mathcal{S}$ ) has an unique solution  $\mathbf{u} \in V$ . Moreover, there exists a constant depending only on  $\Omega$ ,  $C(\Omega) > 0$ , such that:*

$$\|\mathbf{u}\|_{\mathbf{H}^1(\Omega)} \leq \pi C(\Omega). \tag{1}$$

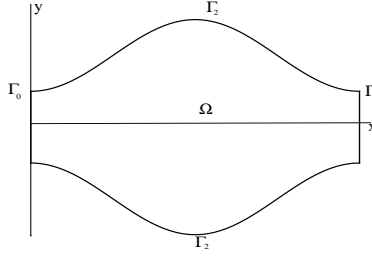


Figure 1: Geometry of channel

*Proof.* Let us note initially that space  $V$  provided the norm  $H^1(\Omega)^2$  being a closed subspace of  $H^1(\Omega)^2$  is thus an Hilbert space. Let us set

$$a(\mathbf{u}, \mathbf{v}) = \int_{\Omega} \nabla \mathbf{u} \cdot \nabla \mathbf{v} d\mathbf{x}, \quad l(\mathbf{v}) = \pi \int_{-1}^{+1} v_1(1, y) dy.$$

It is clear, thanks to the Poincaré inequality, that the bilinear continuous form is  $V$ -coercive. It is easy to also see that  $l \in V'$ . One deduces from Lax-Milgram Theorem the existence and uniqueness of  $\mathbf{u}$  solution of  $(\mathcal{S})$ . Moreover,

$$\int_{\Omega} |\nabla \mathbf{u}|^2 d\mathbf{x} \leq \pi \sqrt{2} \left( \int_{-1}^{+1} |u_1(1, y)|^2 dy \right)^{1/2},$$

i.e.

$$\|\nabla \mathbf{u}\|_{L^2(\Omega)}^2 \leq \pi \sqrt{2} \|\mathbf{u}\|_{L^2(\Gamma)} \leq \pi \sqrt{2} \|\mathbf{u}\|_{H^{1/2}(\Gamma)}.$$

Thanks to the trace Theorem properties, finally one gets

$$\|\nabla \mathbf{u}\|_{L^2(\Omega)}^2 \leq \pi C_1(\Omega) \|\mathbf{u}\|_{H^1(\Omega)},$$

which implies the estimate (1). □

### §3. Equivalent formulation of problem $(\mathcal{S})$

We now will give an interpretation of the problem  $(\mathcal{S})$ . One introduces the space

$$\mathcal{V} = \left\{ \mathbf{v} \in \mathcal{D}(\Omega)^2 ; \operatorname{div} \mathbf{v} = 0 \right\}.$$

Let  $\mathbf{u}$  be the solution of  $(\mathcal{S})$ . Then, for all  $\mathbf{v} \in \mathcal{V}$ , one has

$$\langle -\Delta \mathbf{u}, \mathbf{v} \rangle_{\mathcal{D}'(\Omega) \times \mathcal{D}(\Omega)} = 0.$$

So that thanks to De Rham Theorem, there exists  $p \in \mathcal{D}'(\Omega)$  such that

$$-\Delta \mathbf{u} + \nabla p = 0 \text{ in } \Omega. \quad (2)$$

Moreover, since  $\nabla p \in H^{-1}(\Omega)^2$ , it is known that there exists  $q \in L^2(\Omega)$  such that (see [1])

$$\nabla q = \nabla p \text{ in } \Omega. \quad (3)$$

The open set  $\Omega$  being connected, there exists  $C \in \mathbb{R}$  such that  $p = q + C$ , what means that  $p \in L^2(\Omega)$ . Let us recall that (see [1])

$$\inf_{K \in \mathbb{R}} \|p + K\|_{L^2(\Omega)} \leq C \|\nabla p\|_{H^{-1}(\Omega)^2}.$$

One deduces from the estimate (1) and from (2) that

$$\inf_{K \in \mathbb{R}} \|p + K\|_{L^2(\Omega)} \leq C \|\Delta \mathbf{u}\|_{H^{-1}(\Omega)^2} \leq C \|\mathbf{u}\|_{H^1(\Omega)^2} \leq \pi C(\Omega).$$

Since  $\mathbf{u} \in H^1(\Omega)^2$  and  $\mathbf{0} = -\Delta \mathbf{u} + \nabla p \in L^2(\Omega)^2$ , it is shown that  $-\partial \mathbf{u} / \partial \mathbf{n} + p \mathbf{n} \in H^{-1/2}(\Gamma)^2$  and one has the Green formula: for all  $\mathbf{v} \in V$ ,

$$\int_{\Omega} (-\Delta \mathbf{u} + \nabla p) \cdot \mathbf{v} \, d\mathbf{x} = \int_{\Omega} \nabla \mathbf{u} \cdot \nabla \mathbf{v} \, d\mathbf{x} + \left\langle -\frac{\partial \mathbf{u}}{\partial \mathbf{n}} + p \mathbf{n}, \mathbf{v} \right\rangle, \quad (4)$$

where the bracket represents the duality product  $H^{-1/2}(\Gamma) \times H^{1/2}(\Gamma)$ . Moreover, as  $p \in L^2(\Omega)$  and  $\Delta p = 0$  in  $\Omega$ , one has  $p \in H^{-1/2}(\Gamma)$ . Consequently, one has therefore  $\partial \mathbf{u} / \partial \mathbf{n} \in H^{-1/2}(\Gamma)^2$ . The function  $\mathbf{u}$  being solution of  $(\mathcal{S})$ , for all  $\mathbf{v} \in V$ , one has according to (2) and (4):

$$\left\langle \frac{\partial \mathbf{u}}{\partial \mathbf{n}} - p \mathbf{n}, \mathbf{v} \right\rangle = \pi \int_{-1}^{+1} v_1(1, y) \, dy, \quad (5)$$

i.e.

$$\left\langle \frac{\partial \mathbf{u}}{\partial x} - p \mathbf{e}_1, \mathbf{v} \right\rangle_{\Gamma_1} + \left\langle -\frac{\partial \mathbf{u}}{\partial x} + p \mathbf{e}_1, \mathbf{v} \right\rangle_{\Gamma_0} = \langle \pi \mathbf{e}_1, \mathbf{v} \rangle_{\Gamma_1}, \quad (6)$$

where  $\{\mathbf{e}_i\}$  is the orthonormal basis.

i) Let  $\mu \in H_{00}^{1/2}(\Gamma_1)$  and let us set

$$\mu_2 = \begin{cases} \mu, & \text{on } \Gamma_0 \cup \Gamma_1, \\ 0, & \text{on } \Gamma_2, \end{cases} \quad \text{and} \quad \boldsymbol{\mu} = \begin{pmatrix} 0 \\ \mu_2 \end{pmatrix},$$

where (see [2])

$$H_{00}^{1/2}(\Gamma_1) = \left\{ \varphi \in \mathbf{L}^2(\Gamma_1); \exists \mathbf{v} \in H^1(\Omega), \text{ with } \mathbf{v}|_{\Gamma_2} = \mathbf{0}, \mathbf{v}|_{\Gamma_0 \cup \Gamma_1} = \varphi \right\}.$$

It is checked easily that

$$\boldsymbol{\mu} \in H^{1/2}(\Gamma)^2 \quad \text{and} \quad \int_{\Gamma} \boldsymbol{\mu} \cdot \mathbf{n} \, d\sigma = 0.$$

So that there exists  $\mathbf{v} \in H^1(\Omega)^2$  satisfying (see [3])

$$\operatorname{div} \mathbf{v} = 0 \quad \text{in } \Omega \quad \text{and} \quad \mathbf{v} = \boldsymbol{\mu} \quad \text{on } \Gamma.$$

In particular  $\mathbf{v} \in V$  and according to (6), this yields

$$\left\langle \frac{\partial u_2}{\partial x}, \boldsymbol{\mu} \right\rangle_{\Gamma_1} = \left\langle \frac{\partial u_2}{\partial x}, \boldsymbol{\mu} \right\rangle_{\Gamma_0},$$

which means that

$$\frac{\partial u_2}{\partial x} \Big|_{\Gamma_1} = \frac{\partial u_2}{\partial x} \Big|_{\Gamma_0}. \quad (7)$$

One deduces now from (6) that, for all  $\mathbf{v} \in V$ ,

$$\left\langle \frac{\partial u_1}{\partial x} - p, v_1 \right\rangle_{\Gamma_1} + \left\langle -\frac{\partial u_1}{\partial x} + p, v_1 \right\rangle_{\Gamma_0} = \langle \boldsymbol{\pi}, v_1 \rangle_{\Gamma_1}. \quad (8)$$

But,  $\operatorname{div} \mathbf{u} = 0$  and  $u_2|_{\Gamma_1} = u_2|_{\Gamma_0}$ , one thus has

$$\frac{\partial u_2}{\partial y} \Big|_{\Gamma_1} = \frac{\partial u_2}{\partial y} \Big|_{\Gamma_0} \quad \text{and} \quad \frac{\partial u_1}{\partial x} \Big|_{\Gamma_1} = \frac{\partial u_1}{\partial x} \Big|_{\Gamma_0}. \quad (9)$$

Consequently, thanks to (8) one deduces:

$$\langle -p, v_1 \rangle_{\Gamma_1} + \langle p, v_1 \rangle_{\Gamma_0} = \langle \boldsymbol{\pi}, v_1 \rangle_{\Gamma_1} \quad (10)$$

ii) While proceeding as in i), one shows that

$$p|_{\Gamma_1} = p|_{\Gamma_0} - \boldsymbol{\pi} \quad (11)$$

where the equality takes place with the  $H^{1/2}$  sense. In short, if  $\mathbf{u} \in H^1(\Omega)^2$  is solution of  $(\mathcal{S})$ , then there exists  $p \in L^2(\Omega)$ , unique up to an additive constant, such that:

$$-\Delta \mathbf{u} + \nabla p = \mathbf{0} \quad \text{in } \Omega, \quad (12)$$

$$\operatorname{div} \mathbf{u} = 0 \quad \text{in } \Omega, \quad (13)$$

$$\mathbf{u} = \mathbf{0} \quad \text{on } \Gamma_2, \quad \mathbf{u}|_{\Gamma_1} = \mathbf{u}|_{\Gamma_0}, \quad (14)$$

$$\frac{\partial \mathbf{u}}{\partial x} \Big|_{\Gamma_1} = \frac{\partial \mathbf{u}}{\partial x} \Big|_{\Gamma_0}, \quad (15)$$

$$p|_{\Gamma_1} = p|_{\Gamma_0} - \boldsymbol{\pi}. \quad (16)$$

It is clear that, if  $(\mathbf{u}, p) \in H^1(\Omega)^2 \times L^2(\Omega)$  checks (12)–(16), then  $\mathbf{u}$  is solution of  $(\mathcal{S})$ .

**Theorem 2.** *The problem (12)–(16) has an unique solution  $(\mathbf{u}, p) \in H^1(\Omega)^2 \times L^2(\Omega)$ , up to an additive constant for  $p$ . Moreover,  $\mathbf{u}$  verifies  $(\mathcal{S})$  and*

$$\|\mathbf{u}\|_{\mathbf{H}^1(\Omega)} + \|p\|_{L^2(\Omega)/\mathbb{R}} \leq \boldsymbol{\pi} C(\Omega).$$

*Remark 1.* The pressure verifies the relation (16), which means that  $p$  satisfies the relation of Patankar et al. [5].

### §4. Navier-Stokes Equations

One takes again the assumptions of the Stokes problem given above. For  $\pi \in \mathbb{R}$  given, one considers the following problem

$$(\mathcal{NS}) \left\{ \begin{array}{l} \text{Find } \mathbf{u} \in V \text{ such that} \\ \forall \mathbf{v} \in V, \int_{\Omega} \nabla \mathbf{u} \cdot \nabla \mathbf{v} \, d\mathbf{x} + b(\mathbf{u}, \mathbf{u}, \mathbf{v}) = \pi \int_{-1}^{+1} v_1(1, y) \, dy, \end{array} \right.$$

with

$$b(\mathbf{u}, \mathbf{u}, \mathbf{v}) = \int_{\Omega} (\mathbf{u} \cdot \nabla) \mathbf{v} \cdot \mathbf{w} \, d\mathbf{x}.$$

With an aim of establishing the existence of the solutions of the problem  $(\mathcal{NS})$ , one uses the Brouwer fixed point theorem (see [4, 6]). One will show it.

**Theorem 3.** *The problem  $(\mathcal{NS})$  has at least a solution  $\mathbf{u} \in V$ . Moreover,  $\mathbf{u}$  satisfies the estimate (1).*

*Proof.* To show the existence of  $\mathbf{u}$ , one constructs the approximate solutions of the problem  $(\mathcal{NS})$  by the Galerkin method and then thanks to the compactness arguments, one proves by passing to the limits some convergence properties.

i) For each fixed integer  $m \geq 1$ , one defines an approximate solution  $\mathbf{u}_m$  of  $(\mathcal{NS})$  by

$$\begin{aligned} \mathbf{u}_m &= \sum_{i=1}^m g_{im} \mathbf{w}_i, \quad \text{with } g_{im} \in \mathbb{R}, \\ ((\mathbf{u}_m, \mathbf{w}_i)) + b(\mathbf{u}_m, \mathbf{u}_m, \mathbf{w}_i) &= \langle \pi \mathbf{n}, \mathbf{w}_i \rangle_{\Gamma_1}, \quad i = 1, \dots, m \end{aligned} \quad (17)$$

where  $V_m = \langle \mathbf{w}_1, \dots, \mathbf{w}_m \rangle$  is the vector space spanned by the vectors  $\mathbf{w}_1, \dots, \mathbf{w}_m$  and  $\{\mathbf{w}_i\}$  is an Hilbertian basis of  $V$  which is separable. Let us note that (17) is equivalent to:

$$\forall \mathbf{v} \in V_m, ((\mathbf{u}_m, \mathbf{v})) + b(\mathbf{u}_m, \mathbf{u}_m, \mathbf{v}) = \pi \int_{-1}^{+1} v_1(1, y) \, dy. \quad (18)$$

With an aim to establish the existence of the solutions of the problem  $\mathbf{u}_m$ , the operator as follows is considered

$$\begin{aligned} P_m : V_m &\longrightarrow V_m \\ \mathbf{u} &\longmapsto P_m(\mathbf{u}) \end{aligned}$$

defined by

$$\forall \mathbf{u}, \mathbf{v} \in V_m, ((P_m(\mathbf{u}), \mathbf{v})) = ((\mathbf{u}, \mathbf{v})) + b(\mathbf{u}, \mathbf{u}, \mathbf{v}) - \pi \int_{-1}^{+1} v_1(1, y) \, dy.$$

Let us note initially that  $P_m$  is continuous and

$$\forall \mathbf{u} \in V, b(\mathbf{u}, \mathbf{u}, \mathbf{u}) = 0.$$

Indeed, thanks to the Green formula, one has

$$b(\mathbf{u}, \mathbf{u}, \mathbf{u}) = -\frac{1}{2} \int_{\Omega} |\mathbf{u}|^2 \operatorname{div} \mathbf{u} \, d\mathbf{x} + \frac{1}{2} \int_{\Gamma} (\mathbf{u} \cdot \mathbf{n}) |\mathbf{u}|^2 \, d\sigma = 0,$$

and one takes into account that  $\operatorname{div} \mathbf{u} = 0$  in  $\Omega$  and

$$\int_{\Gamma} (\mathbf{u} \cdot \mathbf{n}) |\mathbf{u}|^2 d\sigma = \int_{\Gamma_0} (\mathbf{u} \cdot \mathbf{n}) |\mathbf{u}|^2 d\sigma + \int_{\Gamma_1} (\mathbf{u} \cdot \mathbf{n}) |\mathbf{u}|^2 d\sigma.$$

Thanks to Brouwer Theorem, there exists  $\mathbf{u}_m$  satisfying (18) and

$$\|\mathbf{u}_m\|_{\mathbf{H}^1(\Omega)} \leq \pi C(\Omega).$$

ii) We can extract a subsequence  $\mathbf{u}_v$  such that

$$\mathbf{u}_v \rightharpoonup \mathbf{u} \text{ weakly in } V,$$

and thanks to the compact imbedding of  $V$  in  $L^2(\Omega)^2$ , we obtain

$$\forall \mathbf{v} \in V, ((\mathbf{u}, \mathbf{v})) + b(\mathbf{u}, \mathbf{u}, \mathbf{v}) = \pi \int_{-1}^{+1} v_1(1, y) dy.$$

As for the Stokes problem, one shows the existence of  $p \in L^2(\Omega)$ , unique except for an additive constant, such that the variational problem  $(\mathcal{N}, \mathcal{S})$  leads to

$$\begin{cases} -\Delta \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} + \nabla p = \mathbf{0} & \text{in } \Omega, \\ \operatorname{div} \mathbf{u} = 0 & \text{in } \Omega, \\ \mathbf{u} = \mathbf{0} & \text{on } \Gamma_2, \\ \mathbf{u}|_{\Gamma_1} = \mathbf{u}|_{\Gamma_0}, \end{cases}$$

with following boundary conditions

$$\begin{aligned} \frac{\partial \mathbf{u}}{\partial x} \Big|_{\Gamma_1} &= \frac{\partial \mathbf{u}}{\partial x} \Big|_{\Gamma_0} \\ p|_{\Gamma_1} &= p|_{\Gamma_0} - \pi. \quad \square \end{aligned}$$

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